

OpenVBI: An Open Source Toolbox for Volunteer Bathymetric Information



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main.d28ynt8exokw88.amplifyapp.com

CSB Pointstore Dashboard Data Centre for Digital Bathymetry

Report Date: 2026-02-24
Total Count: 2,008,966,225
Archive Dates: 2017-04-25 to 2026-02-21
16 orders in the last 30 days

Providers

Rosepoint	1,404,162,637 (70%)
AquaMap	167,140,243 (8%)
Carnival	154,810,211 (8%)
SeaKeepers	116,884,337 (6%)
PGS	54,342,457 (3%)
GLOS	32,270,188 (2%)

Archive Growth

H3 Index 842a30dffffff

Zoom to

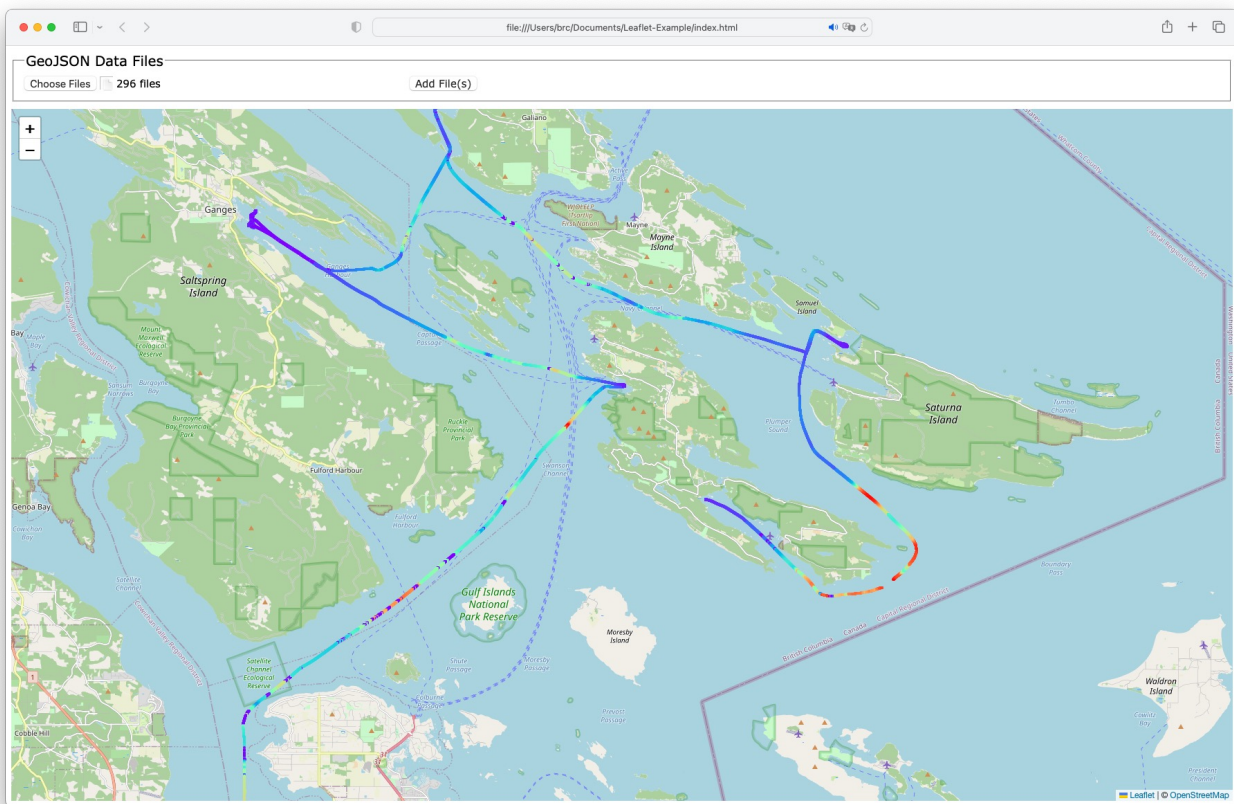
Point Count 328003

2,008,966,225

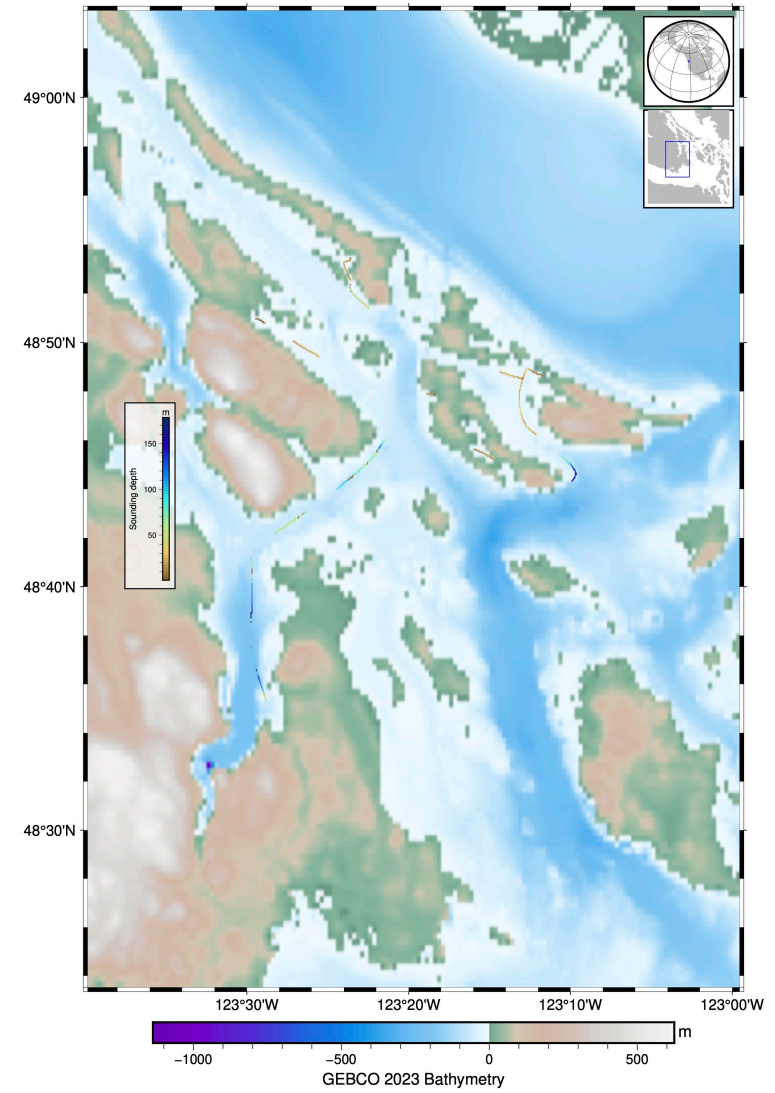
328,003

CHS, Esri, GEBCO, Garmin, NaturalVue | NOAA, NCEI, International Hydrographic Organization, Data Centre for Digital Bathymetry | Esri, TomTom, Garmin, SafeGraph, FAO, METI/NASA, USGS, EPA, NPS, USFWS

Powered by Esri



Soundings from 'Test observer'



Wireless
Bathymetry
Logger

CSB Data Explorer

A view of the data **YOU**ve collected and sent to the IHO DCDB

Map Stats

30 Days

Change Trusted Node

Trusted Node Platform

Organization-wide view

Category	Total Data (bytes)
All Providers	560.3M
FarSounder	2.8M

Available Layers

- Base Map
- US S57 ENCs
- IHO CSB Data
- Your CSB Data

See/Share Platform Stats
Click to view a summary of the data collected by this provider over the selected time window.

Displaying data for:
Trusted Node: FarSounder
NOTE: Data displayed on the map is all time

© OpenStreetMap contributors & NOAA/DCDB CSB Database

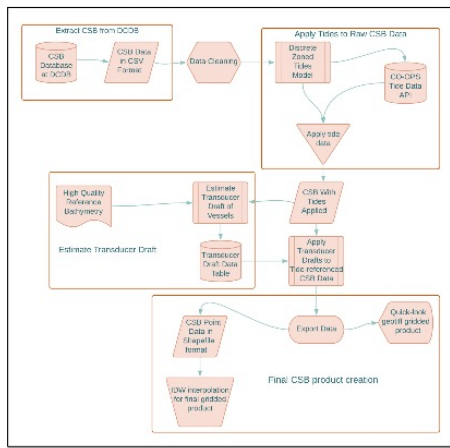


Figure 2: General workflow diagram for CSB processing script

Source: Klemm & Krabiel (US Hydro 2023)

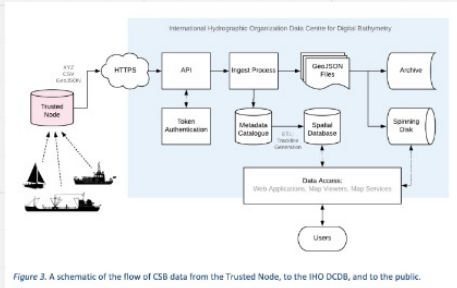
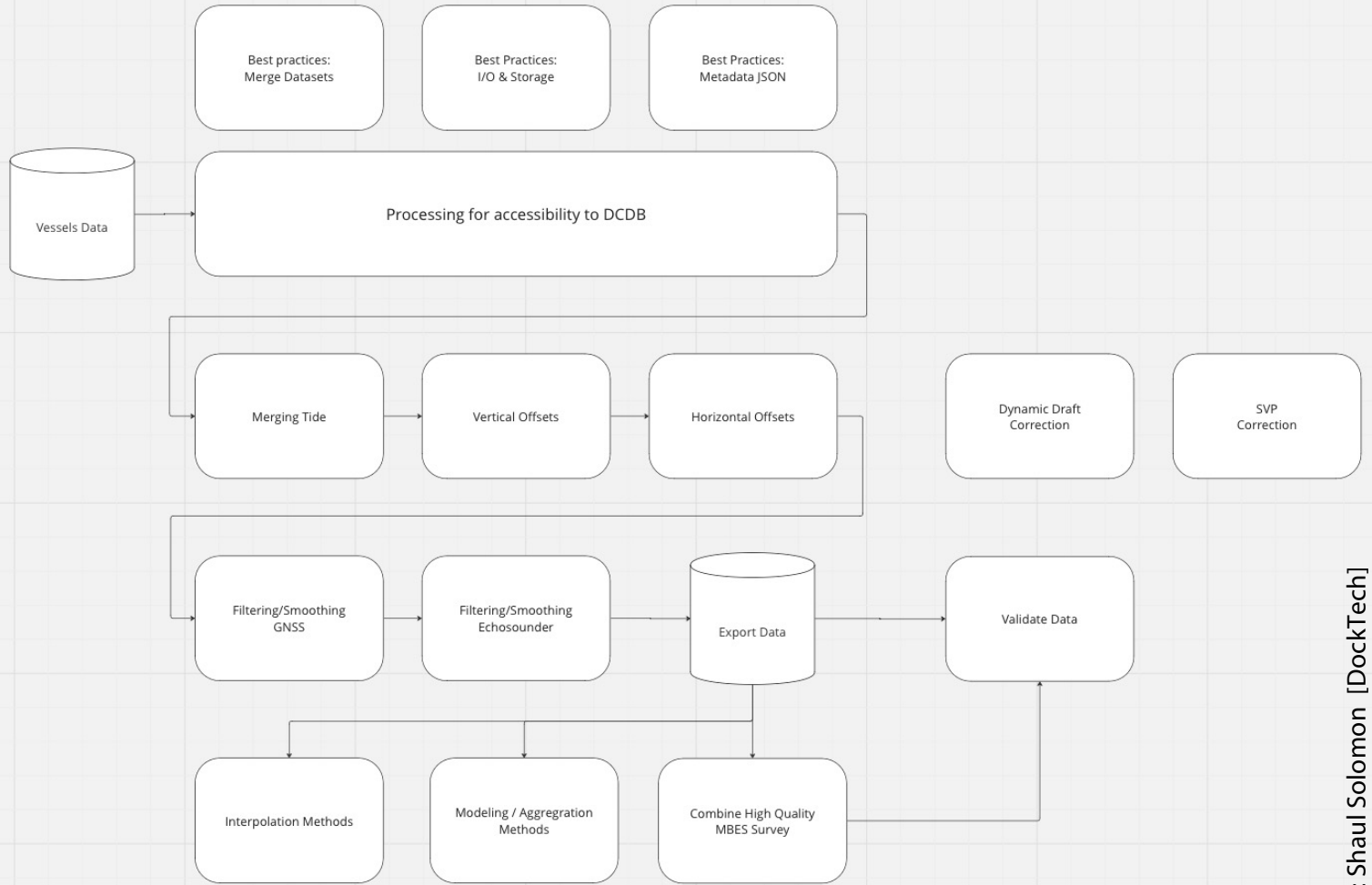


Figure 3: A schematic of the flow of CSB data from the Trusted Node, to the IHO DCDB, and to the public.

Source: DCDB



Source: Shaul Solomon [DockTech]

Why This Matters



Processing
Consistency



Metadata
Construction



Archive
Longevity



Engagement &
Onboarding



- Capture algorithms representing “**best practice**” from community.
- Document **workflow** for VBI/CSB data.
- Provide **strong metadata** management support.
- Cover whole VBI/CSB **data life cycle**: capture → processing → archive → product use.
- Encourage **collaboration** on common problems where possible.

The screenshot displays the GitHub repository for 'OpenVBI'. At the top, the repository name 'OpenVBI' is shown with 'Public' status. Below this, there are navigation options like 'Code', 'Issues', 'Pull requests', etc. A commit history table is visible, listing files and their commit dates. The README file is selected, showing the project title 'OpenVBI' and a description: 'Reference Algorithms for Volunteer Bathymetric Information processing.' The README includes sections for 'Installation' and 'Local installation', with a code snippet for 'pip install'. A QR code is overlaid on the bottom right of the screenshot.

File	Commit Message	Time
.devcontainer	Add vs 3.12 dev container	3 days ago
openvbi	Fix to deduplication algorithm to match new dataframe sp...	2 days ago
.gitignore	Initial commit	2 years ago
Dockerfile.build	Fix: set env var correctly	yesterday
LICENSE	Initial commit	2 years ago
README.md	Add vs 3.12 dev container	3 days ago
pyproject.toml	Initial draft of skeleton for the project (WIP; code not entir...	2 years ago
requirements-build.txt	First pass at waterlevel correctors	last year
requirements.txt	First pass at waterlevel correctors	last year
setup.cfg	Initial draft of skeleton for the project (WIP; code not entir...	2 years ago
setup.py	Initial draft of skeleton for the project (WIP; code not entir...	2 years ago

CCOMJHC / OpenVBI

Code Issues Pull requests **Discussions** Actions Projects Wiki Security 1 Insights Settings

DCDB Updates 2025

Ideas · brian-r-calder

Search: is:open | Sort by: Latest activity | Label | Filter: Open | [New discussion](#)

Categories

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- [Announcements](#)
- [General](#)
- [Ideas](#)**
- [Polls](#)
- [Q&A](#)
- [Show and tell](#)

Most helpful

Be sure to mark someone's comment as an answer if it helps you resolve your question — they deserve the credit! ❤️

Discussions

- [↑ 1](#) **CSB/VBI Tools Workshop at CSBWG17**
brian-r-calder started 3 weeks ago in [Ideas](#) 4
- [↑ 1](#) **DCDB Updates 2025**
enhancement **help wanted**
brian-r-calder started on Aug 6, 2025 in [Ideas](#) 0
- [↑ 1](#) **Outlier detection/Data filtering/Cleaning tool**
ecarle-metservice started on Mar 24, 2025 in [Ideas](#) 2
- [↑ 3](#) **Location of updated NOAA Coast Survey CSB data pipeline scripts**
anthonyklemm started on Mar 11, 2025 in [General](#) 0

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OpenVBI

Generic file adaptors (loggers, archive)

Timestamp generation and interpolation of depth/position.

Generic filtering for initial cleanup.

Generic water level correction (and NOAA Single/Zone corrections)

Rich metadata generation, management, and validation

```
ExampleData - python - 94x30
(openvbi) brc@catfish ExampleData % python
Python 3.11.5 (main, Sep 11 2023, 08:31:25) [Clang 14.0.6 ] on darwin
Type "help", "copyright", "credits" or "license" for more information.
>>> from openvbi.adaptors.ydvr import load_data
>>> data = load_data('00030095.DAT')
>>> type(data)
<class 'openvbi.core.observations.Dataset'>
>>>
```

+ DCDB CSV [r/w] and GeoJSON [w]



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Ref. T (s)	Actual T
0.000	2025-03-11:105557.0
1.010	2025-03-11:105558.0

```
(openvbi) brc@catfish ExampleData % python
Python 3.11.5 (main, Sep 11 2023, 08:31:25) [Clang 14.0.6 ] on darwin
Type "help", "copyright", "credits" or "license" for more information.
>>> from openvbi.adaptors.ydvr import load_data
>>> data = load_data('00030095.DAT')
>>> type(data)
<class 'openvbi.core.observations.Dataset'>
>>> data.generate_observations('Depth')
>>> type(data.depths)
<class 'geopandas.geodataframe.GeoDataFrame'>
>>> data.depths

```

	t	lon	lat	z	u	v	w	geometry
0	1.655582e+09	-82.744197	27.555516	1.32	[-1.0,	-1.0,	-1.0]	POINT (-82.74420 27.55552)
1	1.655582e+09	-82.744197	27.555517	1.29	[-1.0,	-1.0,	-1.0]	POINT (-82.74420 27.55552)
2	1.655582e+09	-82.744196	27.555517	1.17	[-1.0,	-1.0,	-1.0]	POINT (-82.74420 27.55552)
3	1.655582e+09	-82.744197	27.555516	1.35	[-1.0,	-1.0,	-1.0]	POINT (-82.74420 27.55552)
4	1.655582e+09	-82.744197	27.555517	1.25	[-1.0,	-1.0,	-1.0]	POINT (-82.74420 27.55552)
...
740	1.655583e+09	-82.744209	27.555512	1.34	[-1.0,	-1.0,	-1.0]	POINT (-82.74421 27.55551)
741	1.655583e+09	-82.744209	27.555513	1.30	[-1.0,	-1.0,	-1.0]	POINT (-82.74421 27.55551)
742	1.655583e+09	-82.744209	27.555513	1.17	[-1.0,	-1.0,	-1.0]	POINT (-82.74421 27.55551)
743	1.655583e+09	-82.744209	27.555512	1.37	[-1.0,	-1.0,	-1.0]	POINT (-82.74421 27.55551)
744	1.655583e+09	-82.744217	27.555500	1.19	[-1.0,	-1.0,	-1.0]	POINT (-82.74422 27.55550)

```
[745 rows x 6 columns]
>>>
```

3.052	(-82.744197, 27.555518)
4.039	(-82.744203, 27.555535)



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Rich metadata generation, management, and validation

```
ExampleData - python - 94x30
...
740 1.655583e+09 -82.744209 27.555512 1.34 [-1.0, -1.0, -1.0] POINT (-82.74421 27.55551)
741 1.655583e+09 -82.744209 27.555513 1.30 [-1.0, -1.0, -1.0] POINT (-82.74421 27.55551)
742 1.655583e+09 -82.744209 27.555513 1.17 [-1.0, -1.0, -1.0] POINT (-82.74421 27.55551)
743 1.655583e+09 -82.744209 27.555512 1.37 [-1.0, -1.0, -1.0] POINT (-82.74421 27.55551)
744 1.655583e+09 -82.744217 27.555500 1.19 [-1.0, -1.0, -1.0] POINT (-82.74422 27.55550)

[745 rows x 6 columns]
>>> min_time = data.depths['t'].min() + 10*60.0
>>> max_time = data.depths['t'].max() - 10*60.0
>>> from openvbi.filters.timeslot import before_time, after_time
>>> early = before_time(min_time)
>>> late = after_time(max_time)
>>> data = early.Execute(late.Execute(data))
>>> data.depths

      t      lon      lat      z      u      geometry
144 1.655582e+09 -82.744205 27.555514 1.24 [-1.0, -1.0, -1.0] POINT (-82.74421 27.55551)
145 1.655582e+09 -82.744206 27.555514 1.38 [-1.0, -1.0, -1.0] POINT (-82.74421 27.55551)
146 1.655582e+09 -82.744206 27.555515 1.23 [-1.0, -1.0, -1.0] POINT (-82.74421 27.55552)
147 1.655582e+09 -82.744206 27.555514 1.21 [-1.0, -1.0, -1.0] POINT (-82.74421 27.55551)
148 1.655582e+09 -82.744207 27.555514 1.34 [-1.0, -1.0, -1.0] POINT (-82.74421 27.55551)
..
595 1.655582e+09 -82.744197 27.555517 1.16 [-1.0, -1.0, -1.0] POINT (-82.74420 27.55552)
596 1.655582e+09 -82.744198 27.555515 1.36 [-1.0, -1.0, -1.0] POINT (-82.74420 27.55552)
597 1.655582e+09 -82.744198 27.555517 1.22 [-1.0, -1.0, -1.0] POINT (-82.74420 27.55552)
598 1.655582e+09 -82.744198 27.555516 1.32 [-1.0, -1.0, -1.0] POINT (-82.74420 27.55552)
599 1.655582e+09 -82.744199 27.555516 1.19 [-1.0, -1.0, -1.0] POINT (-82.74420 27.55552)

[456 rows x 6 columns]
>>>
```



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Generic water level correction (and NOAA Single/Zone corrections)

Rich metadata generation, management, and validation

```
120
ExampleData - python - 116x35
>>> from openvbi.corrections.waterlevel.noaa import ZoneTides
>>> zone_tide_wl = ZoneTides('NOAA_tide_zones/tide_zone_polygons_new_WGS84_merge.shp')
>>> zone_tide_wl.preload(data)
>>> data.depths

```

	t	lon	lat	z	u	geometry
144	1.655582e+09	-82.744205	27.555514	1.24	[-1.0, -1.0, -1.0]	POINT (-82.74421 27.55551)
145	1.655582e+09	-82.744206	27.555514	1.38	[-1.0, -1.0, -1.0]	POINT (-82.74421 27.55551)
146	1.655582e+09	-82.744206	27.555515	1.23	[-1.0, -1.0, -1.0]	POINT (-82.74421 27.55552)
147	1.655582e+09	-82.744206	27.555514	1.21	[-1.0, -1.0, -1.0]	POINT (-82.74421 27.55551)
148	1.655582e+09	-82.744207	27.555514	1.34	[-1.0, -1.0, -1.0]	POINT (-82.74421 27.55551)
..
595	1.655582e+09	-82.744197	27.555517	1.16	[-1.0, -1.0, -1.0]	POINT (-82.74420 27.55552)
596	1.655582e+09	-82.744198	27.555515	1.36	[-1.0, -1.0, -1.0]	POINT (-82.74420 27.55552)
597	1.655582e+09	-82.744198	27.555517	1.22	[-1.0, -1.0, -1.0]	POINT (-82.74420 27.55552)
598	1.655582e+09	-82.744198	27.555516	1.32	[-1.0, -1.0, -1.0]	POINT (-82.74420 27.55552)
599	1.655582e+09	-82.744199	27.555516	1.19	[-1.0, -1.0, -1.0]	POINT (-82.74420 27.55552)

```
[456 rows x 6 columns]
>>> data = zone_tide_wl.correct(data)
>>> data.depths

```

	t	lon	lat	z	u	geometry
144	1.655582e+09	-82.744205	27.555514	0.514279	[-1.0, -1.0, -1.0]	POINT (-82.74421 27.55551)
145	1.655582e+09	-82.744206	27.555514	0.654287	[-1.0, -1.0, -1.0]	POINT (-82.74421 27.55551)
146	1.655582e+09	-82.744206	27.555515	0.504296	[-1.0, -1.0, -1.0]	POINT (-82.74421 27.55552)
147	1.655582e+09	-82.744206	27.555514	0.484304	[-1.0, -1.0, -1.0]	POINT (-82.74421 27.55551)
148	1.655582e+09	-82.744207	27.555514	0.614312	[-1.0, -1.0, -1.0]	POINT (-82.74421 27.55551)
..
595	1.655582e+09	-82.744197	27.555517	0.439062	[-1.0, -1.0, -1.0]	POINT (-82.74420 27.55552)
596	1.655582e+09	-82.744198	27.555515	0.639075	[-1.0, -1.0, -1.0]	POINT (-82.74420 27.55552)
597	1.655582e+09	-82.744198	27.555517	0.499089	[-1.0, -1.0, -1.0]	POINT (-82.74420 27.55552)
598	1.655582e+09	-82.744198	27.555516	0.599104	[-1.0, -1.0, -1.0]	POINT (-82.74420 27.55552)
599	1.655582e+09	-82.744199	27.555516	0.469117	[-1.0, -1.0, -1.0]	POINT (-82.74420 27.55552)

```
[456 rows x 6 columns]
>>>
```

Observation time (days since 2016-01-01)



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Rich metadata generation, management, and validation

```
Not Secure - csbtools.ccom.unh.edu
OpenVBI - python - 116x54

>>> metadata = md.Metadata()
>>> metadata.setProviderID("OpenVBI", "hello@openvbi.org")
>>> unique_id = "OPNVBI-" + str(uuid.uuid4())
>>> metadata.setIdentifiers(unique_id, "WIBL", "1.5.3")
>>> metadata.setReferencing(md.VerticalReference.TRANSDUCER, md.VerticalReferencePosition.GNSS)
>>> metadata.setVessel('Private Vessel', 'White Rose of Drachs', 65.0)
>>> metadata.addSensor(md.SensorType.SOUNDER, 'Garmin', 'GT-50', [4.2, 0.0, 5.4], draft=1.4, draftUncert = 0.2, frequency = 200000)
>>> metadata.addSensor(md.SensorType.GNSS, 'Litton Marine Systems', 'LMX420', position=None)
>>> metadata.setProcessingFlags(True, True, True)
>>> metadata.setComment('Example metadata only, not valid for post-processing')
>>> metadata.addProcessingAction(md.ProcessingType.VERTREDUCTION, None, reference='ChartDatum', datum='MLLW', method='Observed Waterlevel', model='NOAA Zone Tides')
>>> print(json.dumps(metadata.metadata(), indent=2))
{
  "type": "FeatureCollection",
  "crs": {
    "type": "name",
    "properties": {
      "name": "EPSG:4326"
    }
  },
  "properties": {
    "trustedNode": {
      "providerOrganizationName": "OpenVBI",
      "providerEmail": "hello@openvbi.org",
      "uniqueVesselID": "OPNVBI-ecff4188-0fce-404c-b7c6-06b76c2ae520",
      "convention": "GeoJSON CSB 3.1",
      "dataLicense": "CC0 1.0",
      "providerLogger": "WIBL",
      "providerLoggerVersion": "1.5.3",
      "navigationCRS": "EPSG:4326",
      "verticalReferenceOfDepth": "Transducer",
      "vesselPositionReferencePoint": "GNSS"
    },
    "platform": {
      "uniqueID": "OPNVBI-ecff4188-0fce-404c-b7c6-06b76c2ae520",
      "type": "Private Vessel",
      "name": "White Rose of Drachs",
      "length": 65.0,
      "IDType": "MMSI",
      "IDNumber": "369958000",
      "sensors": [
        {
          "type": "Sounder",
          "make": "Garmin",
          "model": "GT-50",
          "position": [
            4.2,
            0.0,
            5.4
          ],
          "draft": 1.4,
          "draftUncert": 0.2,

```

```
OpenVBI [Dev Container: Python 3 @ desktop-linux]

prep-simple.py x
openvbi > examples > prep-simple.py > ...
1 from openvbi.adaptors.ydvr import load_data
2 from openvbi.filters.thresholding import shoaler_than, deeper_than
3 from openvbi.filters.timeslot import before_time, after_time
4 from openvbi.corrections.waterlevel.noaa import ZoneTides
5 from openvbi.adaptors.dcdb import write_geojson
6
7 # Pull in data from YachtDevices raw binary file, and convert to depths assuming NMEA2000 data
8 data = load_data('00030095.DAT')
9 data.generate_observations('Depth')
10
11 # Calibrate acceptable depth and time windows for data (note that these are simply for
12 # demonstration purposes: this cuts off a lot of valid data!)
13 min_depth = data.depths['z'].min()
14 max_depth = data.depths['z'].max()
15 depth_range = max_depth - min_depth
16 shoal_threshold = min_depth + depth_range/3.0
17 deep_threshold = max_depth - depth_range/3.0
18
19 min_time = data.depths['t'].min() + 10.0*60.0 # Remove first ten minutes
20 max_time = data.depths['t'].max() - 10.0*60.0 # Remove last ten minutes
21
22 # Generate filters for shoal/deep depth, and early/late time
23 shoal = shoaler_than(shoal_threshold)
24 deep = deeper_than(deep_threshold)
25 early = before_time(min_time)
26 late = after_time(max_time)
27
28 # Filter for depth window, and time window
29 data = early.Execute(late.Execute(deep.Execute(shoal.Execute(data))))
30
31 # Correct for waterlevel using NOAA zoned tides and live API for waterlevels
32 zone_tide_wl = ZoneTides('tide_zone_polygons_new_WGS84_merge.shp')
33 zone_tide_wl.preload(data)
34 data = zone_tide_wl.correct(data)
35
36 # Generate B.12-format GeoJSON output
37 write_geojson(data, '00030095.json', indent=2)
38
```

```
OpenVBI [Dev Container: Python 3 @ desktop-linux]

00030095.json x
Users > brc > Projects-Extras > OpenVBI > ExampleData > {} 00030095.json > {} properties > [ ] processing
1 {
2   "type": "FeatureCollection",
3   "crs": {
4     "type": "name",
5     "properties": {
6       "name": "urn:ogc:def:crs:EPSG::31466"
7     }
8   },
9   "properties": {
10    "trustedNode": {
11      "type": "name",
12      "properties": {
13        "name": "OpenVBI"
14      }
15    },
16    "platform": {
17      "type": "name",
18      "properties": {
19        "name": "OpenVBI"
20      }
21    },
22    "processing": [
23      {
24        "type": "TimeStampInterpolation",
25        "timestamp": "2025-03-12T01:55:02.738528Z",
26        "method": "Linear Interpolation",
27        "algorithm": "OpenVBI",
28        "version": "1.0.0"
29      },
30      {
31        "type": "Algorithm",
32        "timestamp": "2025-03-12T01:55:02.739766Z",
33        "name": "ShoalDepth Filter",
34        "source": "OpenVBI",
35        "version": "1.0.0",
36        "comment": "After filtering, total 600 points selected from 745."
37      },
38      {
39        "type": "Algorithm",
40        "timestamp": "2025-03-12T01:55:02.740188Z",
41        "name": "AfterTime Filter",
42        "source": "OpenVBI",
43        "version": "1.0.0",
44        "comment": "After filtering, total 388 points selected from 487."
45      },
46      {
47        "type": "VerticalReduction",
48        "timestamp": "2025-03-12T01:55:04.006713Z",
49        "reference": "ChartDatum",
50        "datum": "MLLW",
51        "method": "Observed Waterlevel",
52        "algorithm": "OpenVBI",
53        "version": "1.0.0",
54        "model": "NOAA Zoned Tides with stations ['8726347']"
55      }
56    ]
57 },
58 "features": [
59   {
60     "type": "Feature",
61     "geometry": {
62       "type": "Point",
63       "coordinates": [
64         -122.5,
65         45.5,
66         10
67       ]
68     }
69   }
70 ]
71 }
72
```



OpenVBI

OpenVBI Workflow Tool

Inputs

Input Directory ...

Output Directory ...

Workflow

Loader ▾

Writer ▾

Depth Message ▾

Metadata File ...

Log Output

```
... metadata update
... output writing
Finishing processing for file [00010077.DAT]
Starting processing for file [00010063.DAT]
... loader
... observation generation
... metadata update
... output writing
Finishing processing for file [00010063.DAT]
Starting processing for file [00010088.DAT]
... loader
... observation generation
... metadata update
... output writing
Finishing processing for file [00010088.DAT]
Starting processing for file [00010089.DAT]
... loader
... observation generation
... metadata update
... output writing
Finishing processing for file [00010089.DAT]
Starting processing for file [00010062.DAT]
... loader
```

Run Statistics

Progress

Succeeded: 33/100 (33.0 %)

Failed: 2/100 (2.0 %)

Total: 35/100 (35.0 %)

Results

Successful Files

```
00010014.DAT
00010015.DAT
00010029.DAT
00010003.DAT
00010017.DAT
00010016.DAT
00010002.DAT
00010065.DAT
00010071.DAT
00010059.DAT
00010058.DAT
00010070.DAT
00010064.DAT
00010072.DAT
00010066.DAT
00010099.DAT
00010098.DAT
00010067.DAT
00010073.DAT
00010077.DAT
00010063.DAT
00010088.DAT
00010089.DAT
```

Failed Files

```
00010038.DAT failed at stage observation generation
00010001.DAT failed at stage loader
```

OpenVBI Workflow Tool

trustedNode

providerOrganizationName

providerEmail

uniqueVesselID

convention

dataLicense

providerLogger

providerLoggerVersion

navigationCRS

verticalReferenceOfDepth

vesselPositionReferencePoint

platform

type

name

length

IDType

IDNumber

sensors

soundSpeedDocumented

positionOffsetsDocumented

dataProcessed

contributorComments

uniqueID

Export

Filename

Actions

What's Next?



OUTLIER
DETECTION &
REMOVAL



PRODUCT
GENERATION



VERTICAL OFFSET
ESTIMATION &
CORRECTION



GLOBAL
WATERLEVEL
CORRECTION



UNCERTAINTY
ESTIMATION



FULL PROCESSING
WORKFLOWS

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Research Professor & Associate Director

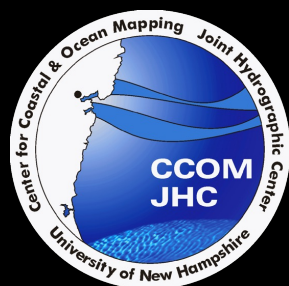
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